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(54) **APPARATUS AND METHOD FOR DATA TRANSMISSIONS IN A TIRE PRESSURE MONITOR**

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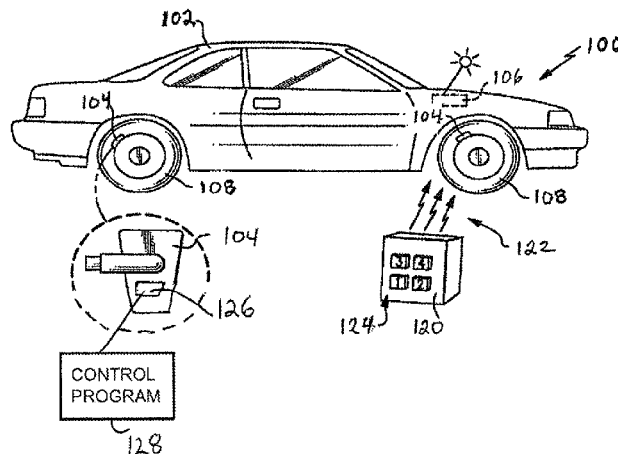
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(57) **ABSTRACT**

A number of frames in a burst is adjusted such that a first optimal number of first frames from a first manufacturer are included in the burst, the first optimal number of frames chosen to enable the detection of the burst by first receivers that are tuned to receive the first frames from the first manufacturer. The number of frames in the burst is adjusted such that a second optimal number of second frames from a second manufacturer are included in the burst, the second optimal number of frames chosen to enable detection of the burst by second receivers that are tuned to receive the second frames from the second manufacturer. The number of frames in the burst maintains a configuration compliant with government regulations regarding one or more of a burst length and a power emission.

14 Claims, 11 Drawing Sheets



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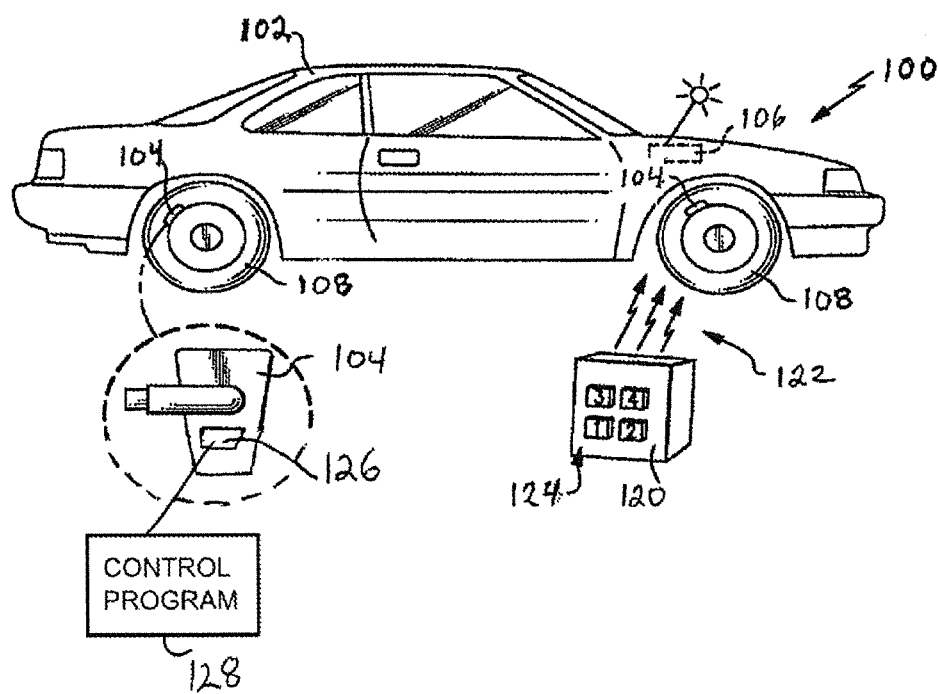


FIG. 1

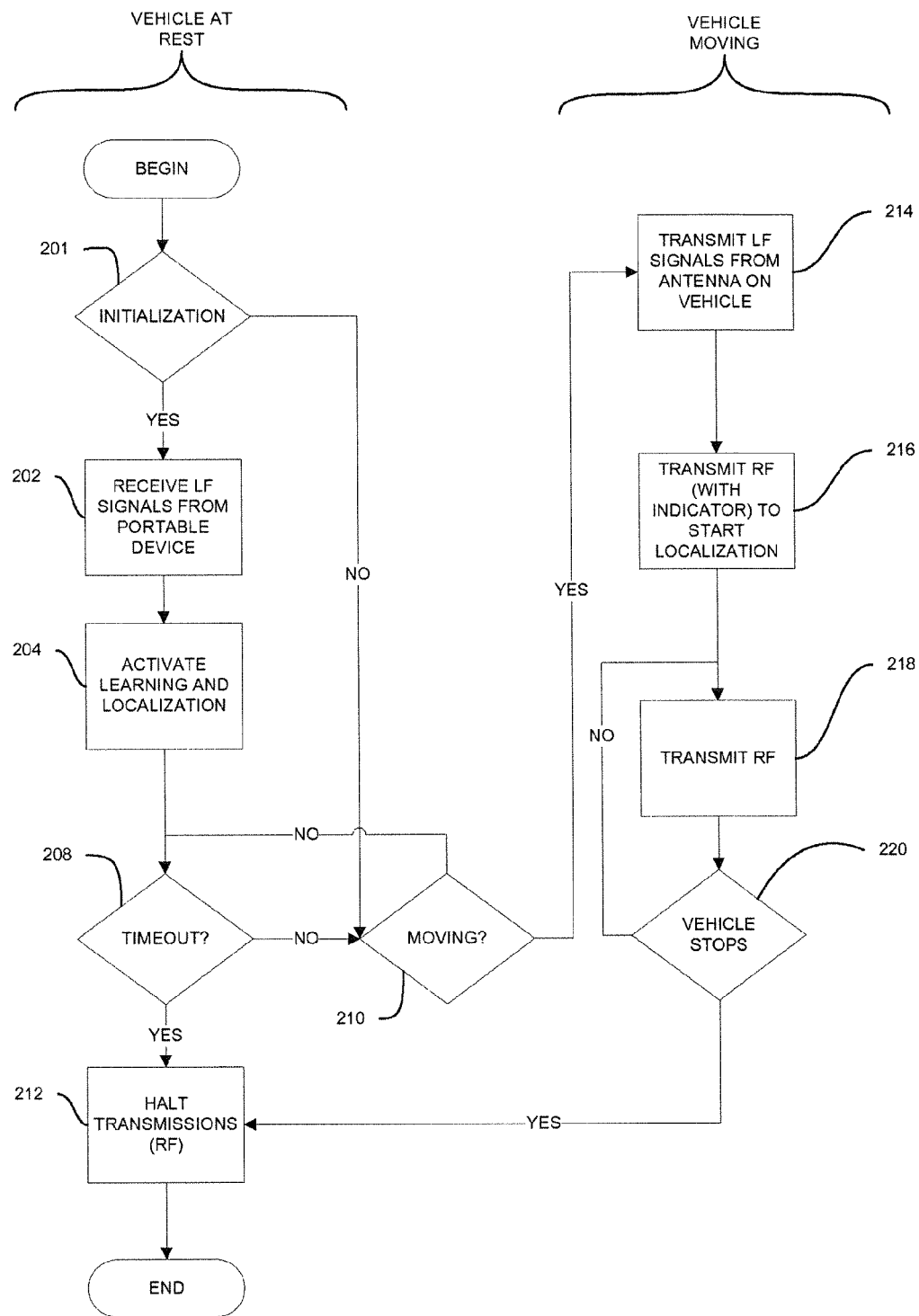


Fig. 2

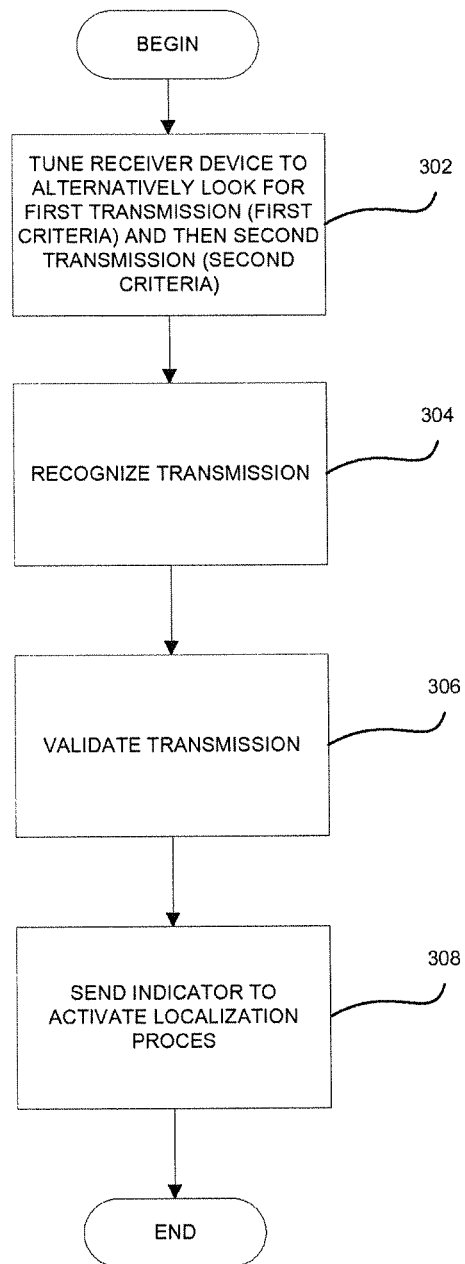


Fig. 3

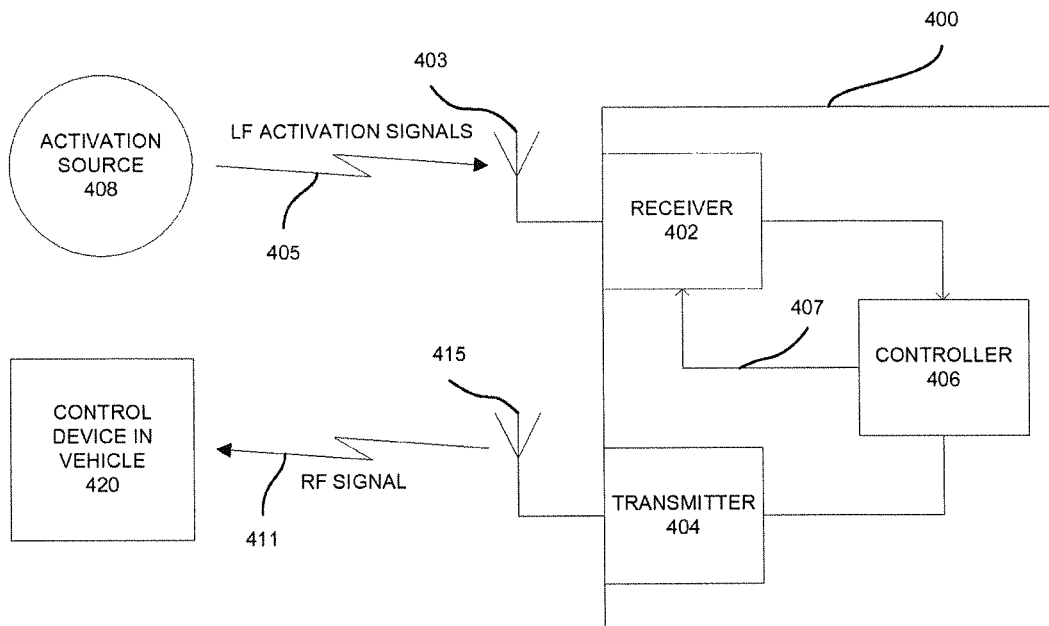


Fig. 4

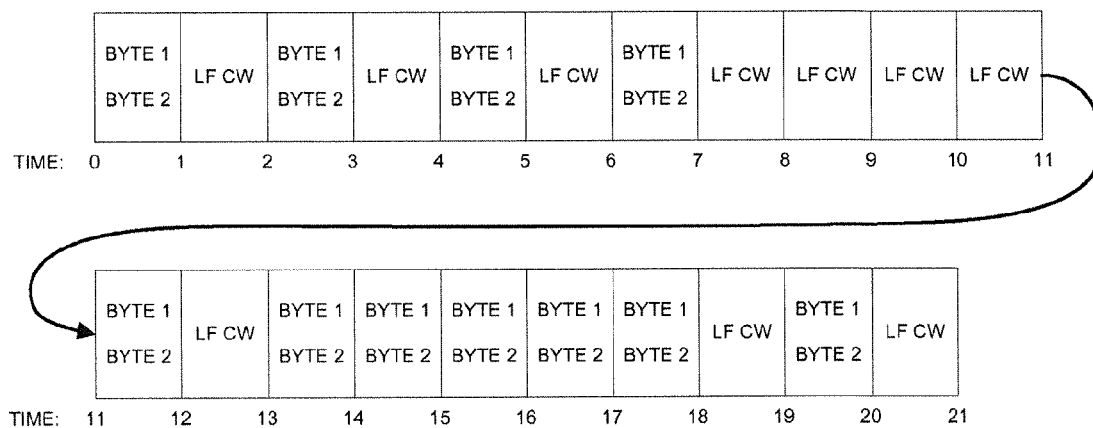


Fig. 5

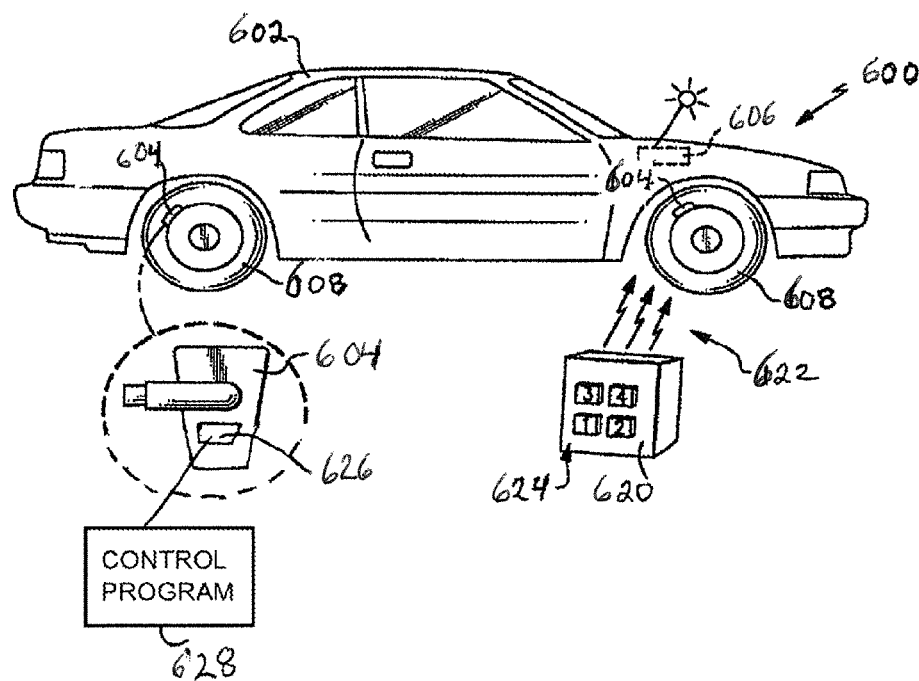


FIG. 6

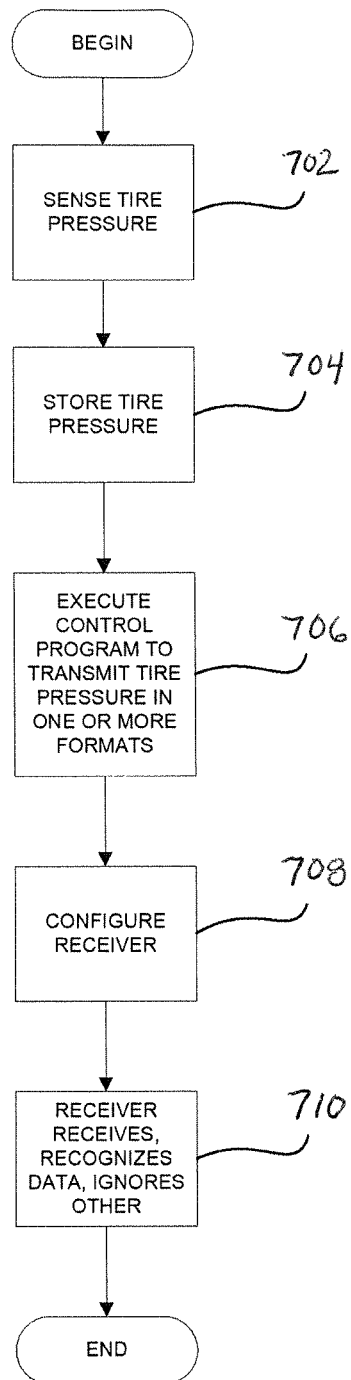


Fig. 7

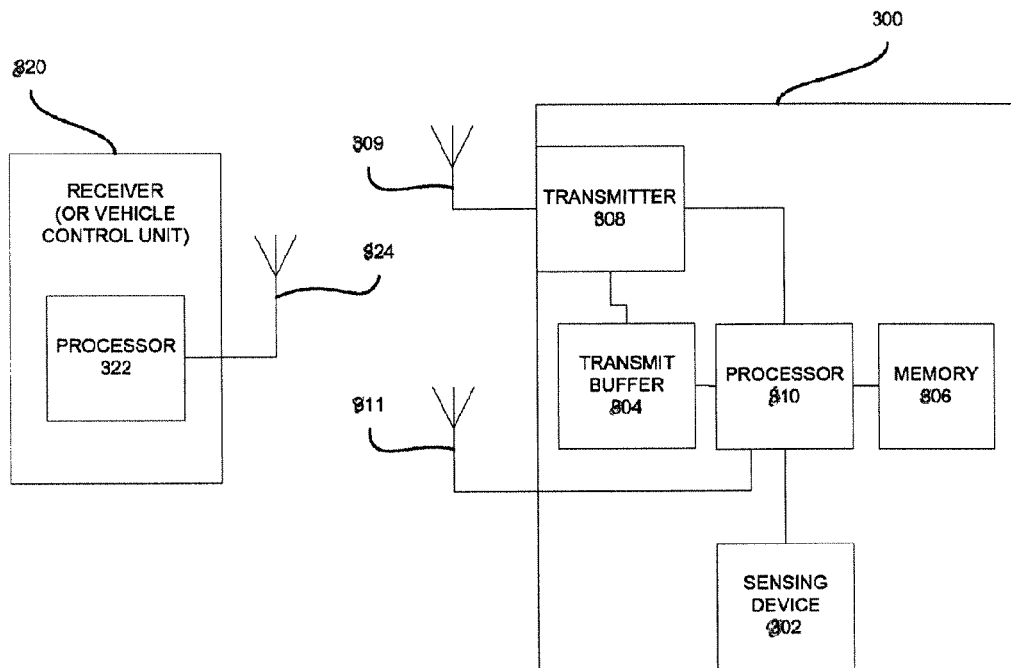


Fig. 8

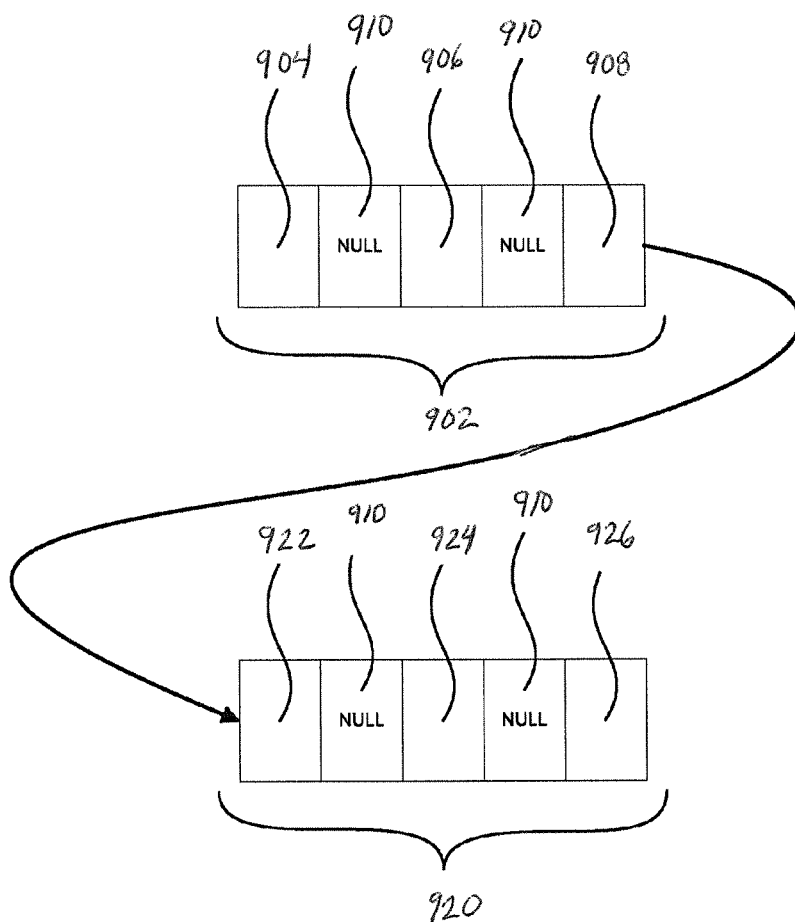


Fig. 9

BURST 1

M1-F2	P1	M2	P2	M1-F2	P3	M3-F1	P4	M4-F1	P5	M4-F2	P6	M1-F2
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BURST 2

M1-F1	P7	M3-F2	P8	M1-F1	P9	M4-F1	P10	M1-F1	P11	M4-F2	P12	M1-F1
-------	----	-------	----	-------	----	-------	-----	-------	-----	-------	-----	-------

BURST 3

M1-F3	P13	M2	P14	M1-F3	P15	M3-F1	P16	M4-F1	P17	M4-F2	P18	M1-F3
-------	-----	----	-----	-------	-----	-------	-----	-------	-----	-------	-----	-------

BURST 4

M1-F2	P19	M3-F2	P20	M1-F2	P21	M4-F1	P22	M1-F2	P23	M4-F2	P24	M1-F2
-------	-----	-------	-----	-------	-----	-------	-----	-------	-----	-------	-----	-------

BURST 5

M1-F1	P25	M2	P26	M1-F1	P27	M3-F1	P28	M4-F1	P29	M4-F2	P30	M1-F1
-------	-----	----	-----	-------	-----	-------	-----	-------	-----	-------	-----	-------

BURST 6

M1-F3	P31	M3-F2	P32	M1-F3	P33	M4-F1	P34	M1-F3	P35	M4-F2	P36	M1-F3
-------	-----	-------	-----	-------	-----	-------	-----	-------	-----	-------	-----	-------

M1-F1 = Manufacturer 1, Format 1
M1-F2 = Manufacturer 1, Format 2
M1-F3 = Manufacturer 1, Format 3
M2 = Manufacturer 2
M3-F1 = Manufacturer 3, Format 1
M3-F2 = Manufacturer 3, Format 2
M4-F1 = Manufacturer 4, Format 1
M4-F2 = Manufacturer 4, Format 2
Pn = Pause

Fig. 10

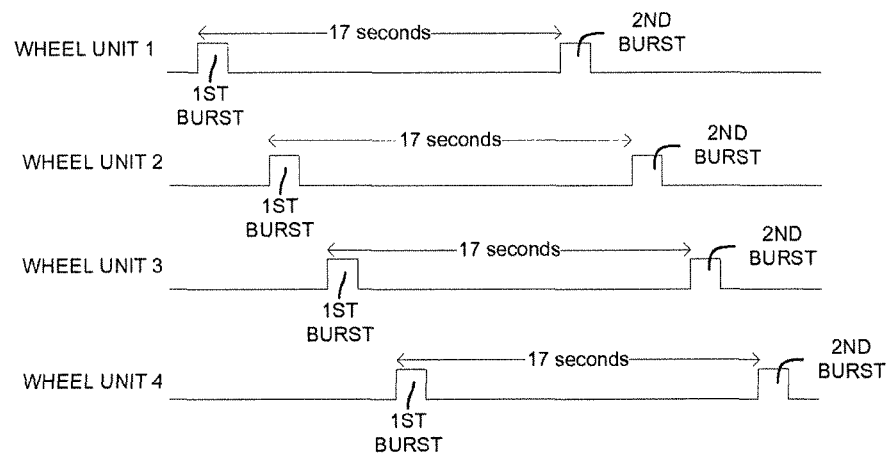


Fig. 11

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APPARATUS AND METHOD FOR DATA TRANSMISSIONS IN A TIRE PRESSURE MONITOR

CROSS REFERENCE TO RELATED APPLICATIONS

This patent is a continuation of US application 20130038442 entitled "Apparatus and Method for Activating a Localization Process for a Tire pressure Monitor," the disclosure of which is incorporated herein by reference in its entirety. This patent also incorporates herein by reference in their entirety the disclosures of US application 20130038441 entitled "Protocol Arrangement in a Tire Pressure Monitoring System", US application 20130038443 entitled "Protocol Misinterpretation Avoidance Apparatus and Method for a Tire Pressure Monitoring System", and US application 20130038440 entitled "Tire Pressure Monitoring Apparatus and Method".

TECHNICAL FIELD

The technical field relates to tire pressure monitoring devices that utilize potentially different transmission protocols.

BACKGROUND

The pressure and other operating parameters of tires are important concerns when operating a vehicle. Not only can incorrect tire pressure (or the incorrect setting of some other tire parameter) lead to inefficient vehicle operation (e.g., the waste of fuel and other problems leading to higher operating costs), but too low a tire pressure (or an inadequate value for some other tire parameter) can lead to safety problems such as accidents. It is difficult and sometimes time-consuming for users to manually measure tire pressure (or other parameters) with a pressure gauge (or other instruments). Consequently, automatic tire pressure monitoring systems have been devised and these systems free the user from manually making tire measurements.

An automatic tire pressure monitoring device typically mounts to a wheel within the tire and wirelessly transmits information indicative of conditions within the tire. The transmissions and the order of information are typically defined by a protocol corresponding to a receiver within the vehicle. Once the receiver receives the information, the information can be processed and presented to a user. For instance, a user can be warned when the pressure in the tires is too high or too low and thus avoid safety problems. Each automobile manufacturer typically has a unique, preferred, and pre-defined protocol to meet application specific needs and applications. Consequently, receivers using one manufacturers' protocol are not responsive to transmitters operating according to other manufacturers' protocols.

Tire pressure monitors also typically need to be activated and/or initialized. Various portable tools can be used for this purpose. Unfortunately, a particular type of tire pressure monitoring device needs to operate with a tool that is compatible with that device. A user has to ensure that the two devices are compatible, or the tire pressure monitor cannot be initialized and/or activated. Consequently, a user needs to worry about compatibility issues and under some circumstances (e.g., when a mismatch is made by the user) the tire pressure monitor cannot be initialized. This results in user dissatisfaction with these previous approaches.

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BRIEF DESCRIPTION OF THE DRAWINGS

FIG. 1 comprises a block diagram of a tire pressure monitoring system according to various embodiments of the present invention;

FIG. 2 comprises a flowchart showing one example of an approach for initializing and/or activating a tire pressure monitor according to various embodiments of the present invention;

FIG. 3 comprises a flowchart showing one example of an approach for initializing and/or activating a tire pressure monitor according to various embodiments of the present invention;

FIG. 4 comprises a block diagram of a tire monitor according to various embodiments of the present invention;

FIG. 5 comprises a block diagram of timeline showing sensing patterns for a receiver device according to various embodiments of the present invention;

FIG. 6 comprises a block diagram of a tire pressure monitoring system according to various embodiments of the present invention;

FIG. 7 comprises a flowchart showing one example of an approach for monitoring pressure and/or other parameters of a tire according to various embodiments of the present invention;

FIG. 8 comprises a block diagram of another example of a tire pressure monitoring system according to various embodiments of the present invention;

FIG. 9 comprises a block diagram of transmission burst formats according to various embodiments of the present invention;

FIG. 10 comprises a block diagram of a burst diagram showing protocol arrangement according to various embodiments of the present invention;

FIG. 11 comprises a timing diagram for signals sent from the various wheel units of a vehicle according to various embodiments of the present invention.

Skilled artisans will appreciate that elements in the figures are illustrated for simplicity and clarity and have not necessarily been drawn to scale. For example, the dimensions and/or relative positioning of some of the elements in the figures may be exaggerated relative to other elements to help to improve understanding of various embodiments of the present invention. Also, common but well-understood elements that are useful or necessary in a commercially feasible embodiment are often not depicted in order to facilitate a less obstructed view of these various embodiments of the present invention. It will further be appreciated that certain actions and/or steps may be described or depicted in a particular order of occurrence while those skilled in the art will understand that such specificity with respect to sequence is not actually required. It will also be understood that the terms and expressions used herein have the ordinary meaning as is accorded to such terms and expressions with respect to their corresponding respective areas of inquiry and study except where specific meanings have otherwise been set forth herein.

DETAILED DESCRIPTION

Approaches are provided where a tire pressure monitoring device can receive and recognize activation signals from a plurality of activation sources, each of these sources potentially transmitting according to different formats, different data contents, and/or different protocols. Consequently, according to the present approaches a user does not have to ensure that a particular activation device is compatible with a particular tire pressure monitor. In fact, the user can simply

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install the tire pressure monitor described herein and activate the device without worrying about compatibility. In one aspect, the approaches described herein can achieve compatibility in the sense that all activation devices can be accommodated. In another aspect, a subset of all possible activation devices can be accommodated, such as the most popular devices to mention one example. By “activation” and as used herein it is meant that a process is executed upon the tire pressure monitor being “activated.” For example, a localization process can be executed. In another example, a control program that transmits RF frames can be executed. Other examples are possible.

In many of these embodiments, a receiver device is tuned to monitor first transmissions at a first time according to a first criterion and to monitor transmissions at a second time according to a second criterion. When the receiver device initially recognizes one of the first transmissions being transmitted according to the first criterion or the second transmissions being transmitted according to the second criterion, the recognized transmission is verified as being valid or authentic. When the transmission is recognized as valid or authentic, an indication is sent to a receiver (e.g., a control unit in a vehicle) and this is effective to activate a localization process that in turn ensures that tire pressure monitoring information can be correlated to a particular tire (with a known identifier) at a known location.

In one aspect, the first criterion describes a low frequency (LF) sinusoidal waveform and the second criterion describes a low frequency (LF) transmission of a predetermined data pattern. Other examples are possible. In another aspect, the verifying includes verifying that the recognized transmission is received for a predetermined time period.

In other aspects, the sensitivity of the receiver device in the monitor can be dynamically adjusted. For example, it can be lowered when the vehicle is not moving and increased when the vehicle is moving.

The transmission of the tire pressure information may be accomplished in a variety of different ways. For instance, a control program may be executed to transmit the tire pressure information according to each of a plurality of communications formats incorporated into the control program and not according to a manufacturers’ code. Transmissions may be made according to each and every possible manufacturers’ protocol or a subset of these protocols. Other examples of transmission approaches are possible.

In others of these embodiments, an apparatus (e.g., a tire pressure monitor) includes a receiver device, a transmitter apparatus, and a controller. The receiver device is configured to receive first transmission and second transmissions from an activation source or sources.

The controller is coupled to the transmitter apparatus and the receiver device. The controller is configured to tune the receiver device to monitor first transmissions at a first time according to a first criterion and to monitor transmissions at a second time according to a second criteria. The controller is further configured to when the receiver device initially recognizes one of the first transmissions being transmitted according to the first criterion or the second transmissions being transmitted according to the second criterion, to verify that the recognized transmission is valid. The controller is still further configured to when the transmission is recognized as valid, send an indication to a receiver so that a localization process can be accomplished. Once the localization process is accomplished, tire pressure information that is sent can be associated with a monitor at a known location.

Thus, approaches are provided where a tire pressure monitoring device can receive and recognize activation signals

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from a plurality of sources, each of these sources potentially transmitting according to different formats, different data contents, and/or different protocols. Consequently, according to the present approaches a user does not have to ensure that a particular activation device is compatible with a particular tire pressure monitor and the user can simply install the monitor and automatically activate the localization process associated with the device without concerns about compatibility.

Referring to FIG. 1, a tire pressure monitoring system 100 is shown assembled within a vehicle 102. The system 100 includes a receiver 106 that receives communications from tire pressure monitoring devices 104 (“monitors”) assembled within each of the vehicle’s tires 108. The receiver 106 may be any communication device configured to receive any type of transmitted communication but tuned to only recognize some of these communications. In one example, these communications are radio frequency (RF) communications, but other types of communications are also possible.

Although the device 104 is described as a tire pressure monitoring device herein, it will be appreciated that this device can gather and transmit other types of information related to the tire in addition to or in place of tire pressure information. For example, the information can include temperature information, acceleration information, or information related to the wear of the treads of the tire. Appropriate sensors or sensing devices may be used to obtain this information. Other examples of information may also be gathered by the tire pressure monitoring device 104.

Each of the tire pressure monitoring devices 104 are assembled within the tires 108 of the vehicle 102 and, as mentioned, communicate information indicative of conditions within the tires 108 to the receiver 106. These conditions include temperature, pressure, and/or any other desired information that aids in the evaluation of tire conditions. Other examples of conditions may also be sensed.

The system 100 includes the tire pressure monitoring devices 104 that in this example includes a memory device 126. The memory device 126 is utilized for the storage of a control program 128. The control program 128, once compiled and executed, transmits sensed information (e.g., tire pressure information) according to one or more protocols (or formats) that govern operation and communication between the tire pressure monitoring device 104 and the receiver 106. Examples of communication protocols that may be used include protocols that specify the frequency and timing of transmissions from the tire pressure monitoring device 104 to the receiver 106 or the format of transmission (such as what constitutes a “1” or a “0,” modulation type, error detection and/or correction content, synchronization pattern, and so forth to name but a few examples in these regards). Tire pressure monitoring information may be transmitted according to the protocols sequentially (e.g., using the same antenna) or at the same time (e.g., using different antennas). No separate manufacturers’ codes are used in making the transmissions. Once the control program is compiled, the protocols that have been selected cannot be changed without changing (e.g., editing, compiling, and installing anew) the control program 128. In one aspect, the control program 128 is compiled and stored in the memory 126 during manufacturing.

In one aspect, the control program 128 may be executed continuously whenever the vehicle is moving. The control program 128 may also be executed when the vehicle is not moving, but only when the sensor is activated externally (i.e., via LF or grounding of a pin on the ASIC during manufacturing). At other times, it may not be executed. However, learning the identities of the devices 104 and/or determining

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where each device is located (“localization”, e.g., front left, front right, and so forth) may be accomplished by using an activation device 120. The activation device 120 emits a wireless signal 122 (e.g., an LF signal) that is received by a corresponding one of the tire pressure monitoring devices 104. Receipt of the wireless signal 122 causes the device 104 to transmit identity information and also indicate to the receiver 106 that the device 104 has received an LF signal and that the localization process can occur. When the vehicle is moving, LF transmitters (e.g., antennas) may transmit LF signals (in place of the device 120). When moving, the RF signals are periodically being transmitted and when the device 104 finds an LF signal, it so indicates to the receiver 106 (e.g., by flipping a bit in the RF transmission). Once this indication is received, localization can be completed (e.g., this process may occur for a predetermined amount of time to ensure that the device 104 is correctly localized). Once localization is complete, tire pressure information can be associated with a known tire. It will be appreciated that in other examples, the control program may itself be activated by the LF signals.

The activation device 120 includes a series of selectable buttons 124 (or other types of actuators) that are actuated by a user to indicate that they wish to activate the tire pressure monitoring device. Although the example device 120 is shown with buttons, other display and selection configurations, such as touch screens, switches or some other selection interface may be used as will be appreciated by those skilled in the art. Accordingly, installation of the multi-application tire pressure monitoring devices 104 optionally includes the initial step of physically activating the tire pressure monitoring devices 104 within each of the corresponding tires 108 or activate a localization process that allows tire pressure data to be associated with particular tires.

If an activation device is used, the activation device 120 is placed proximate to each of the tire pressure monitoring devices 104 to send a signal 122. In one example, the signal 122 is a low frequency transmission received by the proximate tire pressure monitoring device 104.

The devices 104 operate with the receiver 106 in the vehicle and the receiver 106 typically has a display (or some sort of user interface) that is configured to alert the driver when the tire pressure falls below a predetermined threshold value. As mentioned, once physically installed in the tire, the devices 104 are first “learned” by the control unit. During this process, the receiver 106 determines the particular identifiers and during or after learning, a localization process may be executed in which each of the devices 104 is associated with a particular tire.

During normal operation (after the sensors are learned and localized and the vehicle is moving), the device 104 senses the tire pressure and sends a radio frequency (RF) signal to the receiver 106 indicating the tire pressure. The receiver 106 can then determine if a pressure problem exists. If a problem exists, the user can be alerted so that appropriate action can be taken. As mentioned, this is all accomplished by use of a control program that is compiled, translated, and/or assembled before it is executed. In one aspect, once compiled the structure of the control program (e.g., the protocols selected) cannot be changed. Also, nothing external to the device can be input into this control program to change the structure of the control program once the control program (and the protocols specified in the control program) is compiled. It will be appreciated that although many of the examples described herein refer to a control program being executed to transmit RF frames with tire pressure information, that other approaches can also be used. For instance,

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systems that utilize manufacturers’ codes can also have their monitors localized according to the approaches described herein.

The devices 104 can also receive indications as to whether the vehicle is moving. For example, a signal can be sent from the control unit of the vehicle with this information.

Referring now to FIG. 2, one example of an approach for operating a tire pressure monitoring system is described. At step 201, it is determined if the user is attempting to initialize the sensor. If the answer is affirmative, step 202 is performed and if the answer is negative, step 210 is performed. At step 202, LF signals are received from an external activation source. The external source may be a portable or fixed device. The received signals may be sinusoidal signals of a predetermined frequency (CW) or be modulated to include information (e.g., bytes of information). Signals other than LF signals may also be used. The device verifies that the signals are what was expected. When verified, an indicator is transmitted to a receiver (e.g., a control module) that informs the receiver that the monitor has received and verified LF reception.

In another aspect, the type of signals received may affect the operation of the monitor. For instance if LF CW signals are received, bursts have certain formats may be sent. Other examples are possible.

At step 204 and upon verification, the learning process and localization process are performed. Learning refers to obtaining the identifier of a monitor and localization refers to determining where the monitor is located (e.g., front right wheel, front left wheel and so forth). The indicator transmitted by the monitor may be an RF signal of a burst of frames whereby selected ones of the frames include tire pressure information and where a specified predetermined bit is flipped (from a “0” to a “1”, or vice versa) to indicate LF was verified at the monitor. It will be appreciated that the monitor may attempt to verify reception of LF signals a predetermined number of times to ensure that the signal is valid.

At step 208 it is determined if a timeout has occurred (e.g., has a certain period of time passed so that RF transmissions can be halted). If the answer is affirmative, at step 212 transmissions are halted. If the answer is negative, execution continues at step 210 where it is determined whether the vehicle is moving.

If the answer at step 210 is negative, execution continues at step 208 as has been described above. If the answer is affirmative, then at step 214 LF signals are received from LF antennas at the vehicle and are verified as being valid activation signals.

At step 216, an indicator is sent to the receiver to indicate that the monitor has received valid LF signals and the localization process is activated at the receiver (e.g., the vehicle controller). At step 218, the RF transmissions are made and tire pressure information can be associated with a particular monitor at a known location. At step 220, it is determined if the vehicle is stopped, in one example if it has been stopped for a predetermined period of time (e.g., 15 minutes). If the answer is negative, execution continues at step 218 and if the answer is affirmative execution continues at step 212.

Referring now to FIG. 3, one approach for activating a tire pressure monitor is described. At step 302, a receiver device is tuned to monitor first transmissions at a first time according to a first criterion and to monitor transmissions at a second time according to a second criterion. In one aspect, the first criterion describes a low frequency (LF) sinusoidal waveform and the second criterion describes a low frequency (LF) transmission of a predetermined data pattern. In another aspect, the verifying includes verifying that the recognized transmission is received for a predetermined time period.

At step 304, when the receiver device initially recognizes one of the first transmissions being transmitted according to the first criterion or the second transmissions being transmitted according to the second criterion. At step 306, the transmission is recognized as valid and at step 308 an indication is sent to the receiver that the monitor has received a valid LF activation signal and that the localization process can be executed.

After step 308 is accomplished, the tire pressure information can be associated with a known monitor that is at a known location. Consequently, reports can be generated to the user that alert the user when a tire becomes deflated, for example. It will be appreciated that in one aspect tire pressure information can be transmitted periodically when the vehicle is moving. However, it is only after localization is completed that this information can be linked with a monitor that resides at a known location. As used herein, "monitor" refers to the tire pressure monitor such as one of the devices 104 in FIG. 1 or the device 400 of FIG. 4.

Referring now to FIG. 4, an apparatus 400 (e.g., a tire pressure monitor) for initializing a tire pressure monitor includes a receiver device 402, a transmitter apparatus 404, and a controller 406. The receiver device 402 is configured to monitor for first transmission and second transmissions having predetermined formats (that may be present in activation signals 405) received from an activation source or sources 408 via the antenna 403.

The controller 406 is coupled to the transmitter apparatus 404 and the receiver device 402. The controller 406 is configured to tune the receiver device 402 using control signals 407 to monitor for first transmissions at a first time according to a first criterion and to monitor for second transmissions at a second time according to a second criterion. The controller 406 is further configured to when the receiver device 402 initially recognizes one of the first transmissions being transmitted according to the first criterion or the second transmissions being transmitted according to the second criterion, to verify that the recognized transmission is valid (e.g., it matches predetermined requirements such as being of a particular frequency, having a particular value, having a predetermined power level, and so forth). The controller 406 is still further configured to when the transmission is recognized as valid, activate the transmission apparatus 404 to transmit an indicator (e.g., a flipped bit in an RF signal 411) via the antenna 415. This information 411 is transmitted to a vehicle receiver or controller 420 where it may be further processed as described above to initiate the localization process. Although the device 400 may be periodically broadcasting tire pressure information when the vehicle is moving (e.g., in bursts of frames transmitted every approximately 17 seconds) it is only after the localization process is complete that the tire pressure information can be associated with a known tire.

In another aspect, the sensitivity of the LF reception by the receiver device can be adjusted, i.e., it has a dynamic sensitivity. For example, the sensitivity can be lowered when the vehicle is at rest. This may be done, for example, so that when the vehicle is stopped spurious LF signals (e.g., caused by other electronic devices) are not confused as being valid signals. The sensitivity can be increased when the vehicle is moving since there is less of a chance of detecting spurious signals when the vehicle is moving down a roadway.

Referring now to FIG. 5, one example of how a receiver device (e.g., device 402 in FIG. 4) in a monitor is tuned is described. FIG. 5 shows an x-axis that represents time and the time units are expressed in arbitrary units (0, 1 . . . 23). Each time period includes the criteria that a controller (e.g., controller 406 of FIG. 4) has tuned a receiver device (e.g., device

402 of FIG. 4) to listen. For example, between time 0 and 1, the receiver device in the monitor is tuned to listen for LF signals that have a data content of byte 1 and byte 2. Between time 1 and 2, the receiver device in the monitor is tuned to listen for a low frequency (LF) sinusoidal signal (CW). It will be appreciated that these are examples only and that other types of signals can be listened for and in different orders.

Between times 8 and 9, the controller identifies the received transmission as an LF CW transmission. Between time 9 and 12 the receiver device in the monitor is configured to verify this is a valid transmission by listening for the LF CW pattern. For example, the receiver device in the monitor ensures that this is not a noise signal by verifying a constant frequency and/or amplitude to take one example, At time 12, the transmission of RF signals (e.g., using a control program) is enabled. The receiver device in the monitor then alternates between checking/listening for the byte pattern and LF CW patterns described above.

At times 16 and 17, the controller identifies the received transmission as one of the byte patterns byte 1 or byte 2. Between time 17 and 20 the receiver is configured to verify this is a valid transmission by listening for byte 1 or byte 2. For example, the receiver device ensures that this is not a noise signal by verifying that the values of byte 1 or byte 2 do not change. At time 20, the transmission of RF signals (e.g., using a control program) is enabled. The receiver device then alternates between checking for the byte pattern and LF CW patterns described above.

It will be appreciated that in this example the LF CW may be transmitted by one type of activation device (e.g., from a first manufacturer) while the LF byte transmissions are transmitted by another type of activation device (e.g., from a second manufacturer). However, these approaches are applicable to any number of possible received formats and are not limited to two as shown here. The byte patterns may be any byte pattern as is known to those skilled in the art.

Approaches are provided wherein a burst of frames is sent from a tire pressure monitor to a receiver and this burst is constructed to successfully transmit the frames of various manufacturers and, at the same time, meet various criteria such as manufacturers' guidelines, government rules, system functionality, and noise avoidance. The approaches described herein allow the maximum amount of information to be effectively transmitted from the tire pressure monitor within the framework of various requirements. In so doing, an effective multi-application tire pressure monitoring device (e.g., that transmits frames according to the protocols of multiple manufacturers) is provided.

An apparatus for transmitting tire pressure signals includes a transmission buffer and a transmitter. The transmission buffer is configured to store tire pressure monitoring data. The transmitter is configured to transmit a signal including the tire pressure monitoring data. The signal includes a burst that includes plurality of frames and each of the frames includes the tire pressure monitoring information. A plurality of pause spaces may also disposed between at least some of the frames in the burst. Characteristics of the frames in the burst and of the burst itself may be selected based upon one or more criteria such as government standards, industry requirements, periodicity requirements, or power requirements. Other examples of criteria are possible.

The above-mentioned characteristics of the signal that are adjusted based upon the criteria may include the total number of frames in the burst, the relative positioning of the frames within the burst, the number of frames in the burst from each of plurality of manufacturers, and the relative positioning of the frames within the burst wherein at least some of the

frames are from different manufacturers. Other examples of characteristics may also be adjusted.

In one aspect, the power requirement of the frames allows a first power level for a first burst and a second power level for a second burst, the first burst shorter than the second burst, and the first power level being greater than the second power level. In another aspect, the industry requirement relates to the amount of time required to complete a localization process. In still another aspect, the government standard relates to the maximum on-air time for a burst.

Referring to FIG. 6, a tire pressure monitoring system 600 is shown assembled within a vehicle 602. The system 600 includes a receiver 606 that receives communications from tire pressure monitoring devices 604 ("monitors") assembled within each of the vehicle's tires 608. The receiver 606 may be any communication device configured to receive any type of transmitted communication but tuned to only recognize some of these communications. In one example, these communications are radio frequency (RF) communications, but other types of communications are also possible.

Although the device 604 is described as a tire pressure monitoring device herein, it will be appreciated that this device can gather and transmit other types of information related to the tire in addition to or in place of tire pressure information. For example, the information can include temperature information or information related to the wear of the treads of the tire. Appropriate sensors or sensing devices may be used to obtain this information. Other examples of information may also be gathered by the tire pressure monitoring device 604.

Each of the tire pressure monitoring devices 604 are assembled within the tires 608 of the vehicle 602 and, as mentioned, communicate information indicative of conditions within the tires 608 to the receiver 606. These conditions include temperature, pressure, and/or any other desired information that aids in the evaluation of tire conditions. Other examples of conditions may also be sensed.

The system 600 includes the tire pressure monitoring devices 604 that in this example includes a memory device 626. The memory device 626 is utilized for the storage of a control program 628. The control program 628, once compiled and executed, transmits sensed information (e.g., tire pressure information) according to one or more protocols (or formats) that govern operation and communication between the tire pressure monitoring device 604 and the receiver 606. Examples of communication protocols that may be used include protocols that specify the frequency and timing of transmissions from the tire pressure monitoring device 604 to the receiver 606 or the format of transmission (such as what constitutes a "1" or a "0," modulation type, error detection and/or correction content, synchronization pattern, and so forth to name but a few examples in these regards). Tire pressure monitoring information may be transmitted according to the protocols sequentially (e.g., using the same antenna) or at the same time (e.g., using different antennas). No separate manufacturers' codes are used in making the transmissions. Once the control program is compiled, the protocols that have been selected cannot be changed without changing (e.g., editing, compiling, and installing anew) the control program 628. In one aspect, the control program 628 is compiled and stored in the memory 626 during manufacturing.

In one aspect, the control program 628 may be executed continuously whenever the vehicle is moving. The control program 628 may also be executed when the vehicle is not moving, but only when the sensor is activated externally (i.e., via LF or grounding of a pin on the ASIC during manufacturing).

At other times, it may not be executed. However, learning the identities of the devices 604 and/or determining where each device is located ("localization", e.g., front left, front right, and so forth) may be accomplished by using an activation device 620. The activation device 620 emits a wireless signal 622 (e.g., an LF signal) that is received by a corresponding one of the tire pressure monitoring devices 604. Receipt of the wireless signal 622 causes the device 604 to transmit identity information and also indicate to the receiver 606 that the device 604 has received an LF signal and that the localization process can occur. When the vehicle is moving, LF transmitters (e.g., antennas) may transmit LF signals (in place of the device 620). When moving, the RF signals are periodically being transmitted and when the device 604 finds an LF signal, it so indicates to the receiver 606 (e.g., by flipping a bit in the RF transmission). Once this indication is received, localization can be completed (e.g., this process may occur for a predetermined amount of time to ensure that the device 604 is correctly localized). Once localization is complete, tire pressure information can be associated with a known tire. It will be appreciated that in other examples, the control program may itself be activated by the LF signals.

The activation device 620 includes a series of selectable buttons 624 (or other types of actuators) that are actuated by a user to indicate that they wish to activate the tire pressure monitoring device. Although the example device 620 is shown with buttons, other display and selection configurations, such as touch screens, switches or some other selection interface may be used as will be appreciated by those skilled in the art. Accordingly, installation of the multi-application tire pressure monitoring devices 604 optionally includes the initial step of physically activating the tire pressure monitoring devices 604 within each of the corresponding tires 608 or activating a localization process that allows tire pressure data to be associated with particular tires.

If an activation device is used, the activation device 620 is placed proximate to each of the tire pressure monitoring devices 604 to send a signal 622. In one example, the signal 622 is a low frequency transmission received by the proximate tire pressure monitoring device 604.

The devices 604 operate with the receiver 606 in the vehicle and the receiver 606 typically has a display (or some sort of user interface) that is configured to alert the driver when the tire pressure falls below a predetermined threshold value. As mentioned, once physically installed in the tire, the devices 604 are first "learned" by the control unit. During this process, the receiver 606 determines the particular identifiers and during or after learning, a localization process may be executed in which each of the devices 604 is associated with a particular tire.

During normal operation (after the sensors are learned and localized and the vehicle is moving), the device 604 senses the tire pressure and sends a radio frequency (RF) signal to the receiver 606 indicating the tire pressure. The receiver 606 can then determine if a pressure problem exists. If a problem exists, the user can be alerted so that appropriate action can be taken. As mentioned, this is all accomplished by use of a control program that is compiled, translated, and/or assembled before it is executed. In one aspect, once compiled the structure of the control program (e.g., the protocols selected) cannot be changed. Also, nothing external to the device can be input into this control program to change the structure of the control program once the control program (and the protocols specified in the control program) is compiled.

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As mentioned, the devices **604** transmit tire pressure information. The signals that are transmitted include bursts that themselves include plurality of frames and each of the frames includes the tire pressure monitoring information. A plurality of pause spaces may be disposed between at least some of the frames in the burst. Characteristics of the frames in the burst or of the burst itself may be configured based upon criteria such as government standards, industry requirements, receiver requirements, periodicity requirements, or power requirements. Other examples of criteria are possible.

The characteristics of the signal may include the total number of frames in the burst, the relative positioning of the frames within the burst, the number of frames in the burst from each of plurality of manufacturers, and the relative positioning of the frames within the burst wherein at least some of the frames are from different manufacturers. Other examples of characteristics are possible.

The devices **604** can also receive indications as to whether the vehicle is moving. For example, a signal can be sent from the control unit of the vehicle with this information or the device may include an accelerometer.

Referring now to FIG. 7, one example of an approach for transmitting sensed tire pressure information is described. At step **702**, the tire pressure information is sensed. This can be accomplished by any tire pressure sensing mechanism as known to those skilled in the art.

At step **704**, the sensed tire pressure information is stored in a transmission buffer. The transmission buffer may be part of a memory.

At step **706**, a control program is executed to transmit the tire pressure information from the transmission buffer to an external receiver device according to each of a plurality of communications formats incorporated into the control program and not according to a manufacturers' code. The control program may be stored in the same memory as the transmission buffer or may be stored in a separate memory unit.

The control program may be compiled and/or assembled prior to its execution. The transmission of information according to each of the protocols may be in predetermined block having a pre-defined format. Thus, separate blocks are used to transmit tire pressure information for different protocols. Each of the blocks may be transmitted sequentially in a burst. A null space may be used to separate each of the blocks in the burst.

As mentioned, the transmission buffer is configured to store tire pressure monitoring data and the transmitter is configured to transmit a signal including the tire pressure monitoring data. The signal includes a burst that includes plurality of frames and each of the frames includes the tire pressure monitoring information. A plurality of pause spaces in some examples are disposed between at least some of the frames in the burst. Characteristics of the frames in the burst may be selected based upon criteria such as government standards, industry requirements, periodicity requirements, or power requirements. Other examples of criteria are possible.

The characteristics of the signal (e.g., that are adjusted to meet government standards, industry requirements, receiver requirements, periodicity requirements, and/or power requirements) may include the total number of frames in the burst, the relative positioning of the frames within the burst, the number of frames in the burst from each of plurality of manufacturers, and the relative positioning of the frames within the burst wherein at least some of the frames are from different manufacturers. Other examples are possible.

At step **708**, the external receiver device may be configured to operate according to a selected one of the plurality of communication protocols. At the external receiver device

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(that is configured to operate according to a selected one of the plurality of communication protocols) receives the tire pressure information transmitted. At step **710**, the receiver recognizes the tire pressure information transmitted according to the selected one of the plurality of communication protocols and ignores the tire pressure information transmitted according to others of the plurality of communication protocols.

Referring now to FIG. 8, an apparatus **800** for sensing tire pressure information is described. The apparatus **800** includes a sensor **802**, a transmission buffer **804**, a memory **806**, a transmitter **808**, and a processor **810**. One or more antennas **809** transmit RF signals with the tire pressure information (e.g., in blocks, the blocks serially transmitted in bursts, each block having a predetermined format). One or more antennas **811** receive other communications (e.g., LF communications) that activate the apparatus **800** to transmit the RF signals.

The sensor **802** that is configured to sense tire pressure information of a tire. The sensor **802** is any mechanical or electrical sensing arrangement that senses the pressure of the tire as known to those skilled in the art.

The transmission buffer **804** is communicatively coupled to the sensing device and is configured to store the sensed tire pressure information. The transmission buffer **804** may be part of the memory **806** or separate from the memory **806** and is configured to store tire pressure monitoring data. The memory **806** may be any type of memory storage device.

The transmitter **808** is coupled to the transmission buffer **804** and is configured to transmit signals. The transmitter **808** may have one or more antennas **809** to transmit the signals. As mentioned, one or more antennas **811** receive other communications (e.g., LF communications) that activate the apparatus **800** to transmit the RF signals. These antennas may be coupled to the processor **810**, which determines whether the signals meet criteria that are required to activate the apparatus **800** and thereby begin transmitting the tire pressure information. The signal includes a burst that includes plurality of frames and each of the frames includes the tire pressure monitoring information. A plurality of pause spaces is disposed between at least some of the frames in the burst. Characteristics of the frames in the burst may be selected based upon one or more of: government standards, industry requirements, receiver requirements, periodicity requirements, or power requirements. Other examples are possible.

The characteristics of the signal relate to at least one characteristic such as the total number of frames in the burst, the relative positioning of the frames within the burst, the number of frames in the burst from each of plurality of manufacturers, and the relative positioning of the frames within the burst wherein at least some of the frames are from different manufacturers. Other examples are possible.

The processor **810** is communicatively coupled to the sensor **802**, the transmitter **808**, the transmission buffer **804**, and the memory **806**. The processor **810** is configured to execute a control program stored in a memory and execution of the control program is effective to transmit the tire pressure information from the transmission buffer **804** to an external receiver via the transmitter **808** according to each of a plurality of communications formats incorporated into the control program and not according to a manufacturers' code.

In other aspects, a receiver **820** is configured to receive the tire pressure information transmitted according to each of the plurality of communication protocols that is transmitted by the transmitter **808** at antenna **824** and communicate the information to processor **822** where the information can be processed. The receiver **820** is further configured to recognize

the tire pressure information transmitted according to a selected one of the plurality of communication protocols and ignore the tire pressure information transmitted according to non-selected ones of the plurality of communication protocols.

Referring now to FIG. 9, one example of RF transmissions is described. In this example, a first burst 902 includes blocks (or frames) 904, 906, and 908. A second burst 920 includes frames 922, 924, and 926. Null frames 910 are inserted between the frames, 906, 908, 910, 922, 924, and 926.

Each of the blocks or frames 904, 906, 908, 922, 924, and 926 includes tire pressure information. This information may be in the same or different formats. In one example, all frames 904, 906, 908, 922, 924, and 926 include the information according to the protocol of a first manufacturer. In another example, frame 904 is in the protocol of a first manufacturer, frame 906 is according to the protocol of a second manufacturer, frame 908 is in the protocol of the first manufacturer, frame 922 is in the protocol of a third manufacturer, frame 924 is according to the protocol of a fourth manufacturer, and frame 926 is according to the protocol of a fifth manufacturer. In still another example, the frames are in the format of completely different manufacturers. In other aspects, a manufacturer may have different formats. For instance, a first manufacturer may have a first format and a second format.

In one aspect, once the burst is sent, it is repeatedly transmitted. The repetition is immediate and each new burst includes newly updated information transmitted in each frame of the burst. In another example, once the first burst 902 is sent and then a predetermined time later (e.g., 17 seconds) the second burst is sent. Then, the pattern is repeated.

In one aspect, the burst pattern cannot be changed by the user without the control program being entirely re-programmed. That is, a programming tool cannot be used to change the control program to transmit frames for additional/different manufacturers and cannot be used to select frames to transmit.

Referring now to FIG. 10, one example of protocol arrangement is described. As used herein, the term "protocol arrangement" refers to the arrangement of particular manufacturers' frames within a burst so as to meet a predefined criteria. As shown in FIG. 5, the structure of six example bursts is shown. The frames are formatted according to the protocol of Manufacturer 1, with a first format (M1, F1); Manufacturer 1, with a second format (M1, F2); Manufacturer 1, with a third format (M1, F3); Manufacturer 2, with a single format (M2); Manufacturer 3, with a first format (M3, F1); Manufacturer 3, with a second format (M3, F2); Manufacturer 4, with a first format (M4, F1); and Manufacturer 4, with a second format (M4, F2). Pauses (P) are placed between the content-bearing frames. The length of each frame can vary. By "format", it is meant the arrangement and contents of a frame such as the number of bits, the existence of certain fields, the arrangement of the fields, the existence of a checksum field, to mention a few examples.

It will be appreciated that various characteristics of the burst can be changed in the protocol arrangement. These characteristics can include the total number of frames in the burst, the relative positioning of the frames within the burst with respect to each other, the number of frames in the burst from each of plurality of manufacturers, the relative positioning of the frames within the burst where at least some of the frames are from different manufacturers, the frame that leads the burst, to mention a few examples. It will be appreciated that these characteristics can be adjusted based upon a variety of factors such as government standards, industry requirements, periodicity requirements, and power requirements of

the transmitted signal and other system functional requirements. Other examples of characteristics and sources that affect/define these characteristics are possible.

It will be further understood that the particular factors used to select frames (i.e., that are transmitted according to a particular manufacturers' protocol) can vary and that the exact selection varies depending upon the factors mentioned above. These factors can be adjusted to meet the needs of a particular user or system. It will be further appreciated that government and/or industry requirements can change over time, but the approaches herein can take into account any such changes, modifications, additions, or deletions to these requirements.

To take one example, the Federal Communications Commission (FCC) has a requirement that an on-the-air signal can not exceed one second. Further, the periodicity of a burst is also a FCC requirement and is required to be: $P = \text{on-the-air time} * 30$, or 10 seconds, whichever is greatest. A manufacturer may have a periodicity requirement that a burst (or frame) be transmitted every 17 seconds (e.g., because of localization requirements of the manufacturer or so other requirement affecting periodicity). In this case, with $P=17$, the on-the-air time is approximately 500 ms.

Thus, transmissions can be made from each of the wheel units (four, one for each tire) as shown in FIG. 11 with, for example, a duration of 500 ms. As shown, each wheel unit (monitor) sends a burst every 17 seconds. The first burst may be the first burst of FIG. 10, the second burst the second burst of FIG. 10, the third burst, the third burst of FIG. 10, and so forth (for simplicity, the third, fourth, fifth and sixth burst are not shown in FIG. 10).

In other examples, the FCC has stated that for a particular frequency the average power cannot exceed 67.5 db uV/m at three meters. However, for small duration signals, this may be increased by 20 db to 87.5 db uV/m. To determine if a particular portion of a burst exceeds the maximum of 20 db (for a peak value), the base 10 log of (on-the-air time of a frame/100 ms)*20 is taken and this is referred to an averaging factor. Here, the on-the-air time is of the frame itself and does include pauses. For instance, for a frame having a duration of 10 ms, the average factor is 20 db. For a frame with a duration of 20 ms, the averaging factor is 10 db. Thus, in the later case, the averaging factor can be increased by 10 db, for example, by changing the frame to be that of a different manufacturer to increase the duration and the averaging factor. In this example, the frames within the burst are adjusted to obtain (or attempt to obtain) the maximum power at that portion of the burst.

In still other aspects, the number of frames of a particular manufacturer in a burst can be adjusted. For example, some manufacturers require that two or three frames of that manufacturer be transmitted in a burst. The number of frames of a particular manufacturer may also be adjusted depending upon whether the frames are transmitted according to FSK or ASK modulation. For instance, FSK is less susceptible to noise than ASK, so if the frames are ASK-transmitted, more of the ASK type frames may need to be transmitted. The order of frames within a burst can also be adjusted. For example, two frames from a single manufacturer may be transmitted with one frame at the beginning and the other in the middle or end of the burst to avoid noise problems since it is more likely that two frames placed together will be affected by noise rather than two frames spaced apart.

It should be understood that any of the devices described herein (e.g., the programming or activation devices, the tire pressure monitoring devices, the receivers, the transmitters, the sensors, the presentation devices, or the external devices)

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may use a computing device to implement various functionality and operation of these devices. In terms of hardware architecture, such a computing device can include but is not limited to a processor, a memory, and one or more input and/or output (I/O) device interface(s) that are communicatively coupled via a local interface. The local interface can include, for example but not limited to, one or more buses and/or other wired or wireless connections. The processor may be a hardware device for executing software, particularly software stored in memory. The processor can be a custom made or commercially available processor, a central processing unit (CPU), an auxiliary processor among several processors associated with the computing device, a semiconductor based microprocessor (in the form of a microchip or chip set) or generally any device for executing software instructions.

The memory devices described herein can include any one or combination of volatile memory elements (e.g., random access memory (RAM), such as dynamic RAM (DRAM), static RAM (SRAM), synchronous dynamic RAM (SDRAM), video RAM (VRAM), and so forth)) and/or non-volatile memory elements (e.g., read only memory (ROM), hard drive, tape, CD-ROM, and so forth). Moreover, the memory may incorporate electronic, magnetic, optical, and/or other types of storage media. The memory can also have a distributed architecture, where various components are situated remotely from one another, but can be accessed by the processor.

The software in any of the memory devices described herein may include one or more separate programs, each of which includes an ordered listing of executable instructions for implementing the functions described herein. When constructed as a source program, the program is translated via a compiler, assembler, interpreter, or the like, which may or may not be included within the memory.

It will be appreciated that any of the approaches described herein can be implemented at least in part as computer instructions stored on a computer media (e.g., a computer memory as described above) and these instructions can be executed on a processing device such as a microprocessor. However, these approaches can be implemented as any combination of electronic hardware and/or software.

Those skilled in the art will recognize that a wide variety of modifications, alterations, and combinations can be made with respect to the above described embodiments without departing from the spirit and scope of the invention, and that such modifications, alterations, and combinations are to be viewed as being within the scope of the invention.

What is claimed is:

1. A method of forming a burst of frames for transmission in a tire pressure monitoring system, the method comprising: adjusting a number of frames in a burst such that a first optimal number of first frames from a first manufacturer are included in the burst, the first optimal number of frames chosen to enable the detection of the burst by first receivers that are tuned to receive the first frames from the first manufacturer;

adjusting the number of frames in the burst such that a second optimal number of second frames from a second manufacturer are included in the burst, the second optimal number of frames chosen to enable detection of the burst by second receivers that are tuned to receive the second frames from the second manufacturer;

wherein the number of frames in the burst maintains a configuration compliant with government regulations regarding one or more of a burst length and a power emission, wherein the burst comprises an on-the-air signal and the on-the-air signal does not exceed one second,

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wherein the burst is transmitted at a particular frequency and the average power does not exceed 67.5 db uV/m at three meters, and wherein the burst configuration cannot be changed by the user without a control program being entirely re-programmed.

2. The method of claim 1, wherein the burst has a configuration compliant with an industry requirement.

3. The method of claim 2, wherein the industry requirement relates to the amount of time required to complete a localization process.

4. An apparatus for transmitting tire pressure signals, the apparatus comprising: a transmission buffer configured to store tire pressure monitoring information; a transmitter configured to transmit a signal including the tire pressure monitoring information, the signal comprising: a burst with an adjustable number of frames such that a first optimal number of first frames from a first manufacturer are included in the burst, the first optimal number of frames chosen to enable the detection of the burst by first receivers that are tuned to receive the first frames from the first manufacturer; such that a second optimal number of second frames from a second manufacturer are included in the burst, the second optimal number of frames chosen to enable detection of the burst by second receivers that are tuned to receive the second frames from the second manufacturer; wherein the burst maintains a configuration compliant with government regulations regarding a one or more of a burst length and a power emission, wherein the burst comprises an on-the-air signal and the on-the-air signal does not exceed one second, wherein the burst is transmitted at a particular frequency and the average power does not exceed 67.5 db uV/m at three meters, and wherein the burst configuration cannot be changed by the user without a control program being entirely re-programmed.

5. The apparatus of claim 4, wherein the burst has a configuration compliant with an industry requirement.

6. The apparatus of claim 5, wherein the industry requirement relates to the amount of time required to complete a localization process.

7. A method of forming a burst of frames for transmission in a tire pressure monitoring system, the method comprising: disposing first frames of a first manufacturer at a first position in a burst, and disposing second frames of a second manufacturer at a second position in the burst, the first position being sequentially earlier in time than the second position; wherein the length of the first frames is shorter than the length of the second frames; wherein the burst pattern cannot be changed by the user without the control program being entirely re-programmed, wherein the burst comprises an on-the-air signal and the on-the-air signal does not exceed one second, wherein the burst is transmitted at a particular frequency and the average power does not exceed 67.5 db uV/m at three meters, and wherein the burst configuration cannot be changed by the user without a control program being entirely re-programmed.

8. The method of claim 7, wherein the burst has a configuration compliant with an industry requirement.

9. The method of claim 8, wherein the industry requirement relates to the amount of time required to complete a localization process.

10. An apparatus for transmitting tire pressure signals, the apparatus comprising: a transmission buffer configured to store tire pressure monitoring information; a transmitter configured to transmit a signal including the tire pressure monitoring information, the signal comprising: a burst including first frames of a first manufacturer at a first position in the burst, and second frames of

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a second manufacturer at a second position in the burst, the first position being sequentially earlier in time than the second position; wherein the length of the first frames is shorter than the length of the second frames; wherein the burst pattern cannot be changed by the user without the control program being entirely re-programmed, wherein the burst comprises an on-the-air signal and the on-the-air signal does not exceed one second, wherein the burst is transmitted at a particular frequency and the average power does not exceed 67.5 db uV/m at three meters, and wherein the burst configuration cannot be changed by the user without a control program being entirely re-programmed.

11. The apparatus of claim 10, wherein the burst has a configuration compliant with an industry requirement.

12. The apparatus of claim 11, wherein the industry requirement relates to the amount of time required to complete a localization process.

13. A non-transitory computer usable medium having a computer readable program code embodied therein, said computer readable program code adapted to be executed to implement a method, the method comprising: adjusting a number of frames in a burst such that a first optimal number of first frames from a first manufacturer are included in the burst, the first optimal number of frames chosen to enable the detection of the burst by first receivers that are tuned to receive the first frames from the first manufacturer;

adjusting the number of frames in the burst such that a second optimal number of second frames from a second manufacturer are included in the burst, the second opti-

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mal number of frames chosen to enable detection of the burst by second receivers that are tuned to receive the second frames from the second manufacturer;

wherein the burst maintains a configuration compliant with government regulations regarding one or more of a burst length and a power emission, wherein the burst comprises an on-the-air signal and the on-the-air signal does not exceed one second, wherein the burst is transmitted at a particular frequency and the average power does not exceed 67.5 db uV/m at three meters, and wherein the burst configuration cannot be changed by the user without a control program being entirely re-programmed.

14. A non-transitory computer usable medium having a computer readable program code embodied therein, said computer readable program code adapted to be executed to implement a method, the method comprising: disposing first frames of a first manufacturer at a first position in a burst, and disposing second frames of a second manufacturer at a second position in the burst, the first position being sequentially earlier than the second position; wherein the length of the first frames is shorter than the length of the second frames; wherein the burst pattern cannot be changed by the user without the control program being entirely re-programmed, wherein the burst comprises an on-the-air signal and the on-the-air signal does not exceed one second, wherein the burst is transmitted at a particular frequency and the average power does not exceed 67.5 db uV/m at three meters, and wherein the burst configuration cannot be changed by the user without a control program being entirely re-programmed.

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